

CS 6210 Fall 2016

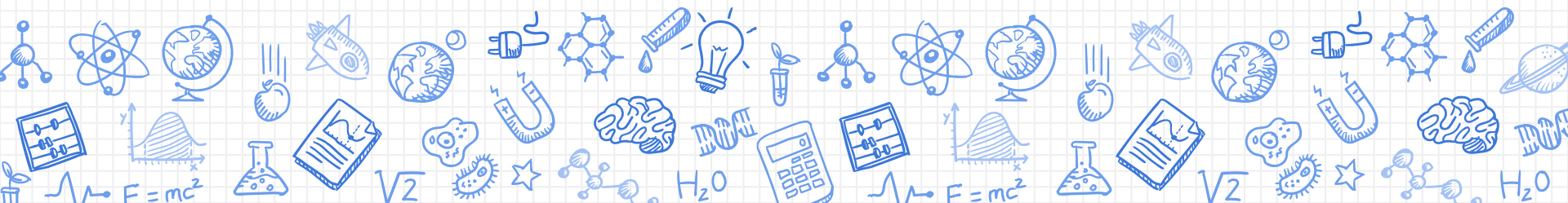
Bei Wang

Review Lecture

What have we learnt in Scientific Computing?

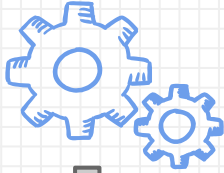
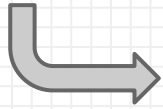


Let's recall the scientific computing pipeline

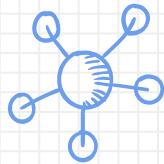
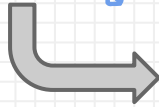




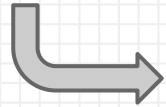
observed
phenomenon



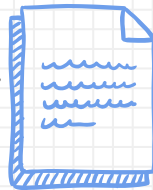
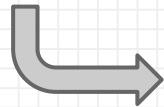
mathematical
model



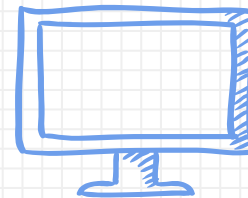
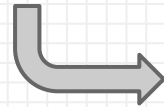
discretization
solution algorithm



efficiency
accuracy
robustness



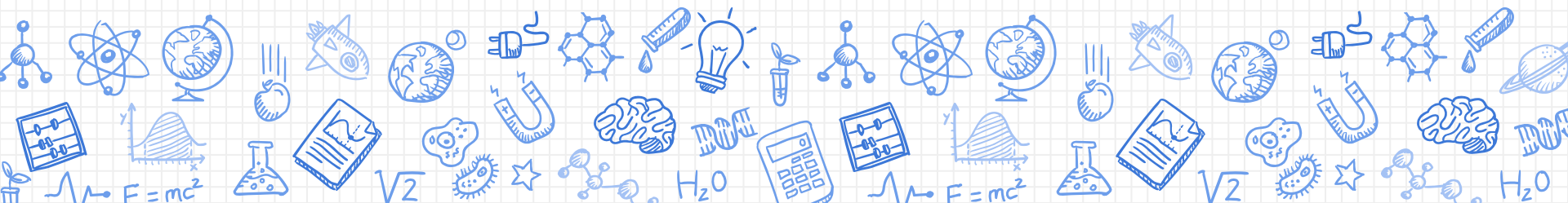
implementation



programming
environment
data structure
computing
architecture

Scientific
Computing

We have accomplished our goal
and learnt a great deal!



Our Supercomputing Miniseries

Mark Kim (SCI): Fixed-Rate Compressed Floating-Point Arrays

Sidharth Kumar (SoC): Parallel I/O Library

Arnab Das and Vinu Joseph (SoC): Why we are not ready for Exascale Computing?



Linear algebra

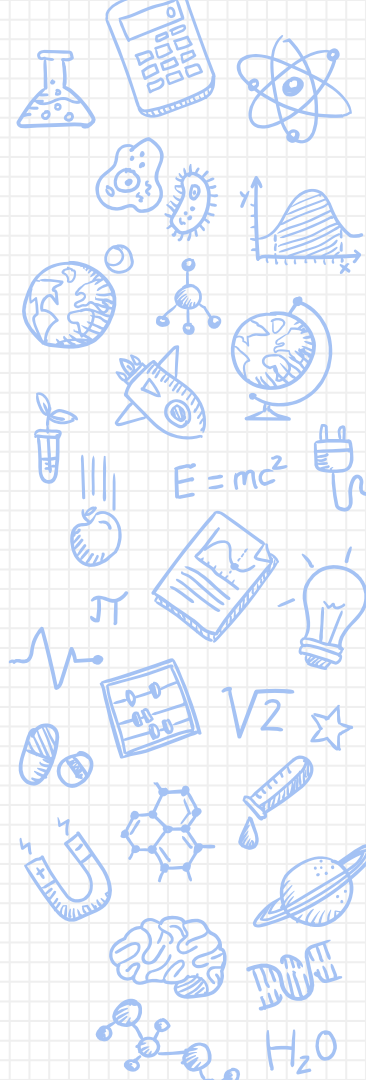
Vector norm

Matrix norm

*Symmetric positive definite

Orthogonal matrices

*SVD



Linear Systems $Ax = b$: direct methods

Backward and forward substitution

*Gaussian elimination

*LU decomposition

Pivoting

*Cholesky decomposition

Error estimation

Condition number



Linear least squares: $\min \|b - Ax\|$

Uniqueness and normal equation: $(A^T A)x = A^T b$

Orthogonal transformation

*QR

Householder transformation

Gram-Schmidt orthogonalization



Eigenvalues and singular values: $Ax = \lambda x$; SVD

Power method for computing dominant eigenvalue and eigen vectors

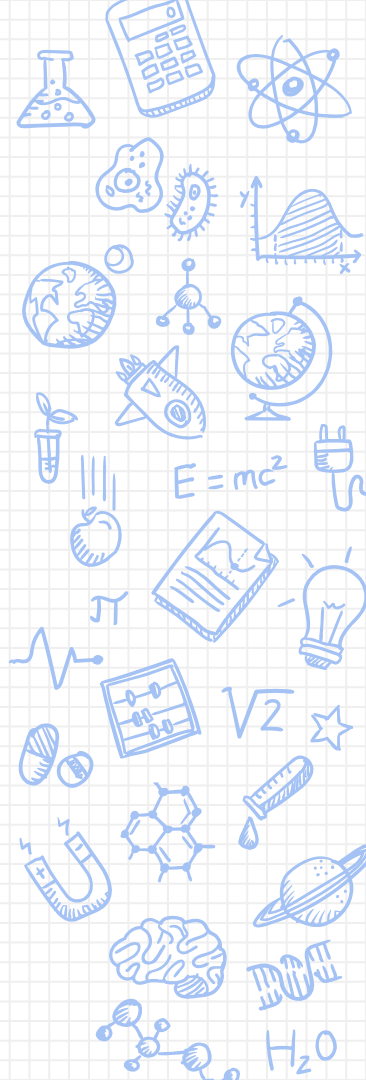
*SVD

Best lower rank approximation

*Geometric intuition behind SVD

Least squares via SVD

QR for eigenvalues



Nonlinear systems $f(x) = 0$ and optimization

Newton's method

Unconstrained optimization

Taylor's series

Gradient descent

Linear search

Quasi-Newton



Polynomial interpolation $f(x) = \sum c \phi(x)$

*Piecewise linear

Piecewise constant

Monomial interpolation

*Lagrange interpolation

Divided difference (coefficients) $f[x_i \dots x_j]$

*Error

*Chebyshev interpolation

Interpolating derived values f', f''



Piecewise polynomial interpolation

Broken line

Piecewise Hermite interpolation

Cubic spline

Parametric curves



Best approximation

Continuous least squares approximation

Orthogonal basis function: Legendre polynomial

Weighted least squares

*Chebyshev polynomial: geometric intuition



Numerical differentiation

*Taylor series

2 point, 3 point, 5 point formula

Richardson extrapolation

Using Lagrange polynomial interpolation

Roundoff errors



Notes on final exam

Open book, open notes, close internet

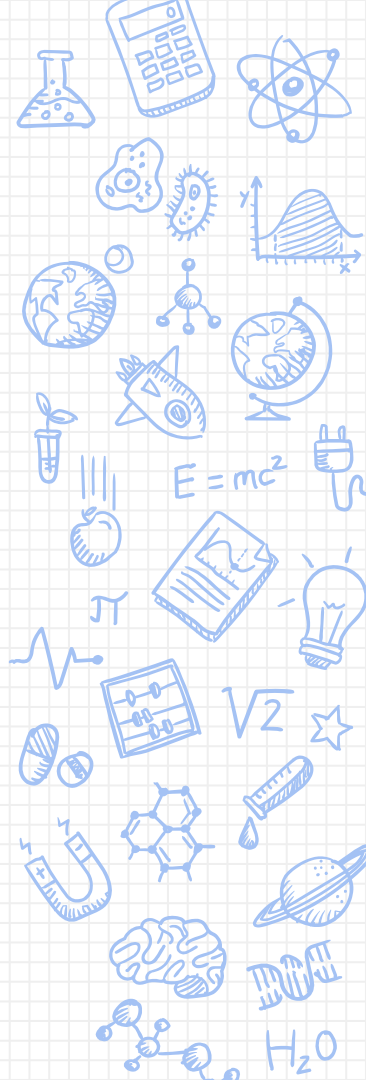
Please bring your calculator (recommended); TA will have a calculator that you can borrow, if needed.

20 T/F questions (2 points each)

5-10 questions that require derivation

10 T/F question for extra credits

1 extra derivation question for extra credits



Example questions

1. In unconstrained optimization, a necessary condition for having a global min at point x is for x being a critical point (T/F)?
2. Give polynomial interpolation to some data using different interpolation schemes.



Answer to the questions

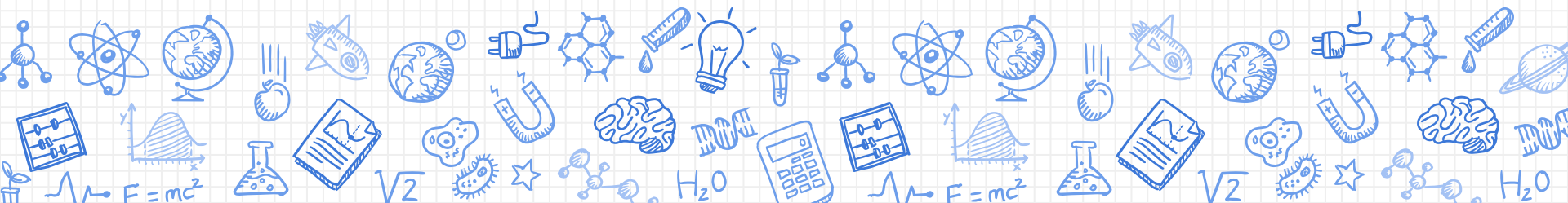
In unconstrained optimization, a necessary condition for having a global min at point x is for x being a critical point (T/F)?

False: Page 260. A necessary condition for having a local minimum at x is that x be a critical point and that the symmetric Hessian matrix being positive semidefinite.



Revisit: The Future of Scientific Computing 50 years from now

[Trefethen 2000]



2

Fully intelligent, adaptive numerics

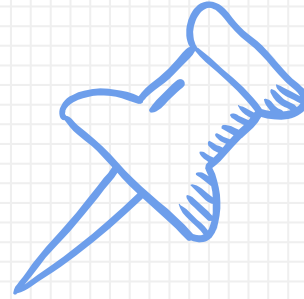
Numerical computing will be adaptive, iterative, exploratory, intelligent – computational power will be beyond your wildest dreams.

Everything is embedded in an iterative loop, problems solved atop an encyclopedia of numerical methods



3

Loss of determinism



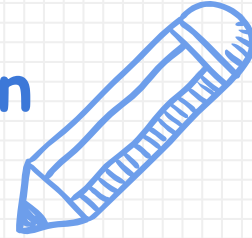
Determinism in numerical computing will be gone.

It is not reasonable to ask for exactness in numerical computation...we may not ask for repeatability either.



4

Floating point arithmetic: best general purpose approximation

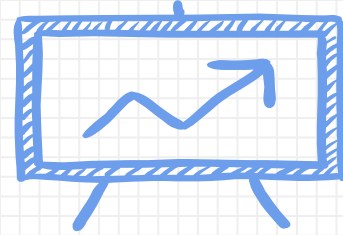


The importance of floating point arithmetic will be undiminished.

128 bit plus word lengths, most numerical problems can not be solved symbolically still, still need approximations.

5

The quest for speed in matrix multiplication



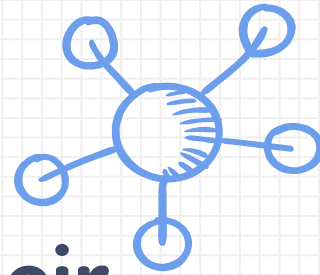
Linear systems of equations will be solved in time $O(N^{2+e})$

Complexity of matrix multiplication = complexity of “almost all” matrix problems: inverse, determinants, solve linear systems...

How fast can we multiply two n by n matrices? Standard $O(N^3)$.

Strassen’s algorithm $O(N^{2.81})$. Coppersmith and Winograd’s algorithm $O(N^{2.38})$...Is $O(N^2)$ achievable?

6 Multipole methods



Multipole methods and their descendants will be ubiquitous.

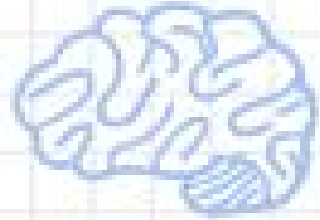
Speed up the calculation of long-ranged forces in the n-body problem. Large-scale numerical computations rely more on approximate algorithms...more robust and faster than exact ones.

8

massive parallel computing

The problem of massively parallel computing will have been blown open by ideas related to human brain.

Understanding human brain and its implications for computing.

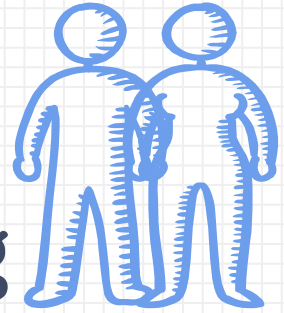


9

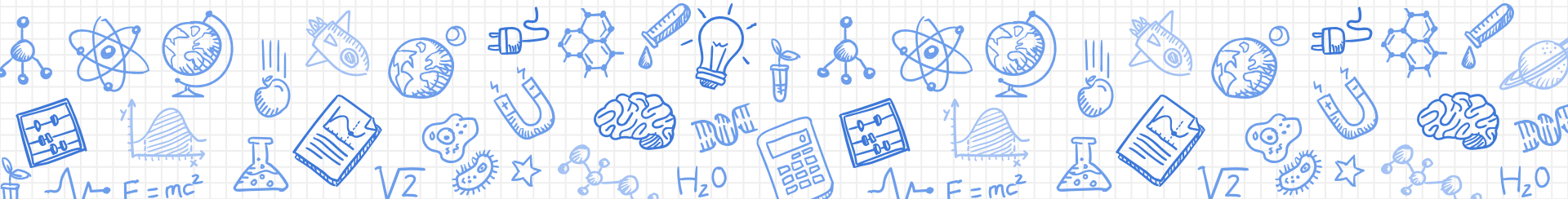
New programming methods

Our methods of programming will have been blown open by ideas related to genomes and natural selection.

Think digitally about the evolution of life in earth.



What's your prediction of the future of scientific computing?





Take home message

1. **Think Big:** how SC could transform your research?
2. **Keep your eyes open:** identify the newest advancement in SC.
3. **Master the fundamentals:** practice makes perfect.
4. **Have some fun while learning!**

TA Friday (12/8) review hour: 1:30 p.m - 2:30 pm

Extra Notes

So it goes.

